



"FFTplace BestFit enables to find the best alignment of components next to each other for subsequent assembly steps, taking care of all environmental influences."

one step ahead in **INTELLIGENT** production systems





FFT*place* **BestFit**

Find the best possible position for your component.

FFT*place* **BestFit** - Operation How to align components to the best position



FFTplace BestFit - Advantages

Constant quality, fast measurement, reduced costs

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FFT*place* **BestFit** - System features

Easy to use and high efficient in keeping quality standards



FFT*place* **BestFit** - Equipment

Hardware & Software



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References More than 20 significant projects

FFT*place* **BestFit** Light Concept description





F1

Optimised alignment of components





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Introduction

- Target:
 - Optimised alignment of components to each other.

Task:

- Each component is affected with tolerances to be compensated.
- This step eliminates further intervention in subsequent assembly steps

→ Solution: **FFT**place **BestFit** Operation:

- Constant calculation of aligned position
- Visibility of inaccuracy is compensated



Process flow





Operating without FFT place BestFit

Position correction with the 3-2-1 method

- Alignment of the component to 2 edges
 - Gaps on these two edges are correct
 - Deviation of the gaps to the remaining edges, as the component is not aligned in average to all edges.

 \rightarrow No mediated alignment of the component





Adjustment of the position with the BestFit Operation







Statistical optimisation of the starting position



Process flow



Scanning ot the deviation

- Component in measuring position
- Automatic optimisation of the measuring position



Data logging

- Sensors measure gap and transition of the components
- Punch measurement is also possible



Data transfer

 Sensor data are transferred to FFT VarioInspector



Process flow



Corrective calculation

 Calculation of the **FFT**place **BestFit** position



Transfer of data

- The calculated
 FFTplace **BestFit** position is transferred
- Transfer of data via
 TCP/IP



Repositioning

The position of the component is optimised



FFTplace BestFit Quality Assurance

- After assembly and release of the component, an actual status recording is carried out.
- The result is used for:
 - Visualisation on screen
 - Transfer to higher-level QA systems
 - Generation of reports and statistics
 - Influences on further assembly steps are included







2 **FFT***place* **BestFit** - Advantages

Consistant quality, fast measurement, reduced costs





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FFTplace BestFit - Advantages

Saving costs and increasing efficiency

- Cost cutting by reducing rework
- Enables Short cycle time
- Very high availability

Optimisation and assurance of quality

- Improvement of quality
- Radius-independent
 measurement
- Quality measurement result of each component is stored
- No influence of the operator



FFTplace BestFit - Advantages

Advantages in detail..



Repeatability

Repeatability taking into account all tolerances of each single parts



100% of high-class documentation

100% quality documentation of each component \rightarrow Quality data available for further processing



Direct, optimum alignment

Short, closed tolerance loop

→ direct response to each single part with its own tolerances



Elimination of environmental impacts

Elimination of environmental influences such as temperature, aging robots and changes in positioning behaviour



Easy to handle and efficient in maintaining quality

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Technical characteristics of the system

Flexibility	Serveral versions are handled by one system	
Resolution	Sensor	0,05mm
Availability	System	99,92%
Verfication of stability	cg - value (per sensor)	> 1.33 (static)
	cp - value (System with robot)	> 1.33 (dynamic)



Strategy in case of sensor failure

In event of a sensor failure, learned data will be applied

Production can be continued until repairment is scheduled

Any sensor can be replaced within 3 minutes

Stored calibration data will enable the replaced sensor

No calibrations on reference points necessary





Fast implementation based on simulation technology

- Setup of sensor positions based on CAD data
- Sensor positions are verified by simulation
- Design of tools / simulation based on CAD models
- Adaption of the software parallel to the implementation phase (setup of the measuring point)
- No reference tool required









Hardware & Software

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Vario Gauge DH 3



FFT Image processing - hardware



FFT VarioGauge DH (Twinsensor)

- · Perfect for stable measurements of gaps with higher precision
- · Fixing via quick release system plate
- Data transmission via Gigabit Ethernet
- Also usable on painted body





FFT VarioGauge V6 2.5D (Triangle sensor)

- Measurement of 2.5D applications (for gap and flush measurement)
- Implemented µC (calibration data are stored in sensor)
- adjustable resolutions and laser intensities
- Optional: Protection against dust/dirt & sunlight
- Also available as 2D sensor (for round holes and rectangular holes)





FFT Image processing – Hardware



Wenglor Sensor

- · 1-dimensional measurement of distance on flat surfaces
- Economic & good solution for measurement of shaft dimensions
- Works in FFT sensor network
- (Can be implemented in FFT sensor bus.)





FFT VarioGauge - Hub

- Connection of up to 6 sensors
- Connection of up to 4 Wenglor sensors
- Several hubs can be used in series





FFT Image Processing – Software

The FFT VisionGuide and VisionAnalyser software combine the various modules of the image processing system into one software with convenient user interface



FFT VisionGuide

- BestFit calculation algorithm
- Exchange of data (PC Roboter; PC PLC)
 - Interbus-S, Profibus-DP, Ethernet / Profinet
 - KUKA KRC1 KRC4 (incl. VKRCx)
- Logging / saving of all process-relevant data and quality features into database





FFT VisionAnalyser

- Image processing
- Sensor communication
- Definition & setup of the measurement characteristic





FFT Image processing – Software



FFT VisionReport

- The web-based VisionReport runs on a separate server
- The software is designed for processing data of several FFT BestFit production lines for visualization
- Worldwide access to the quality database





Database server

- Designed as RAID System
 - RAID = Redundand Array of Independent Disks
- Secure data archiving
- Secure storage of the setups of all FFT BestFit "slaves"
- MySQL, MSSQL & MariaDB





FFT Image proccessing- Software (VisionReport)





FFT Image Processing – Hardware & Software, System connections





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We support your project from the idea to the realization and gladly beyond.



We take into account quality and deadline requirements and we assume the responsibility for the project until turnkey handover.



Consulting Use our experience for your tasks



Project Management Support from the idea to the start of production



Identification of risks in the process



Custom design Creation of individual solutions



Manufacturing Successful manufacturing with modern technologies



Documentation Clear and logical



Conformity Compliance with standards and regulations



After Sales Competent service through FFT





5 **FFT***place* **BestFit** - References

More than 20 reference projects





one step ahead in INTELLIGENT production systems



FFTplace BestFit - References

Some references from the Automotive Industry

Projekt: BMW F45, F40

Rear doors, Front doors, Fender-Brackets, Fenders, Trunk-lid, Bonnet-hinges & bonnet



Projekt: VW Tiguan

BestFit trunk lid, hang in doors



Projekt: VW ID.3

BestFit trunk lid

Highlight: Final assembly painted body



Projekt: BMW G26

Rear doors, front doors, fender-brackets, fenders, bonnet & bonnet-hinges





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Concept description



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FFTplace BestFit - Light

principle





FFTplace BestFit - Light

the interaction of measuring robot and joining robot





FFTplace BestFit - Light

example with LaserRadar Sensor

Test setup with the Nikon LaserRadar in the BestFit cell in Fulda.





- The joining robot is KUKA
- Measuring robot is FANUC
- LaserRadar was used instead of the FFT Doublehead



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NetForm&Pierce



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FFT NetForm&Pierce

What is FFT's Vision Controlled NetForm&Pierce?

It is a powerful system-solution that allows the creation of quality-relevant surfaces and holes best fitting to the tolerances of each body i.e. form and pierce taillamp area using FFT BestFit Light





FFT – NF&P References

- SEM China, Chrysler Voyager
- Valmet Finland, Mercedes A-Klasse
- Compas Mexiko



We support our customers in efficiently implementing their production systems according to their specifications.

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